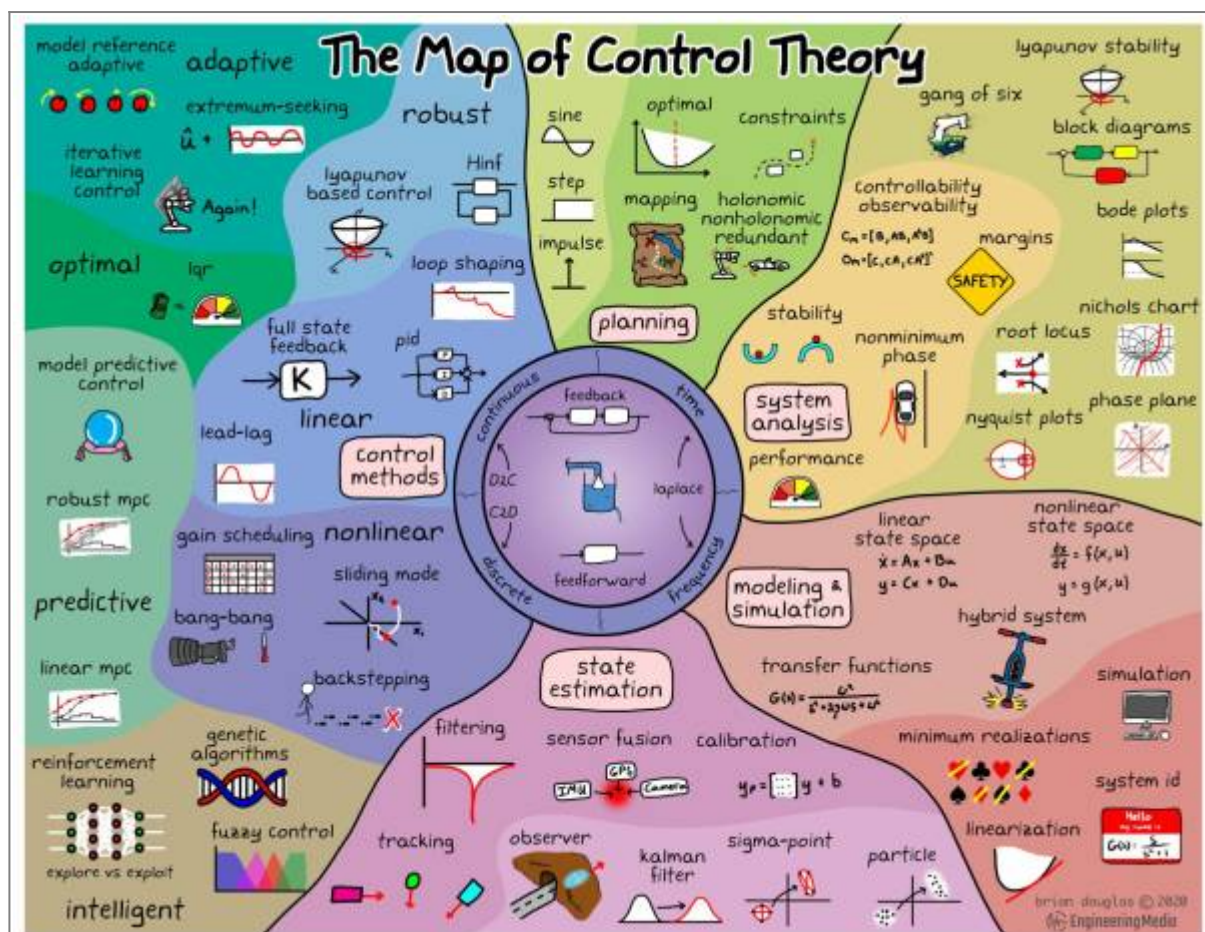


EMRP2022

Closed loop control

PID Control Theory

https://www.youtube.com/watch?v=wkfEZmsQqiA&list=PLn8PRpmsu08pQBgjxYFXSsODEF3Jqmm-y&ab_channel=MATLAB



<https://engineeringmedia.com/map-of-control> Fig. 1

Inverted Pendulum with PID

Optimal control of inverted pendulum system using PID controller, LQR and MPC

<https://iopscience.iop.org/article/10.1088/1757-899X/263/5/052007/pdf>

Stabilising an Inverted Pendulum Controller with PID controller

https://www.matec-conferences.org/articles/mateconf/pdf/2018/11/mateconf_eureca2018_02009.pdf

Control the Ryze Tello Drone from Python

- **tello-pathon** code by Harley Lara: <https://github.com/harleylara/tello-python>
- **RyzeTelloHSRW** code by Ilgar Rasulov (EligoSoftware):
https://github.com/eligosoftware/ryzetellohsrw/blob/main/basic_follow.py

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