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## **Workshop Notes**

### **Preparation / Prerequisits**

- Download ...
- Install ...
- Print ...

### Introduction

- The work of the EOLab Team → Current state of development
- Image Classification
- · Object detection
- · Mini drones with OD

#### **Hands On**

- Connect SNAP to the server in Nvidia Jetson
- Image classification game
- Object Detection ??

### Reflection

## **Main Achievements (internal discussion)**

# SNAP! and Mini-Drone (Harley, 3 mins, live, with Alonzo pilot)

- Tello SNAP Backend (Javascript backend, communication software interface, Wifi, client, binding to IP address), URL, eolab.de github
  - One drone has a default IP, it is in "station" mode (the drone is AP, AP mode), 192.168.10.1
  - Tello AP mode (client to Wifi), necessary for more than one drone in network and/or interaction with Jetson
- Tello SNAP! category (collection of SNAP! Javascript blocks), websocket interaction with the interface talking to the drone
- https://wiki.eolab.de/doku.php?id=drones:mini drones:snap tello

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# Jetbot and Object Detection with SNAP! (Ali, 3 mins, with Alonzo driver)

- Object follower
- Jetbot Camera
- SNAP! is running remotely, could be running on Jetbot
- DetectNet (SSD-MobileNet V2, CoCo Dataset, 91 Classes)
- Closed Loop Control
- TODO: Short video!

# Object Detection: Follow an Object with Drone (Ilgar, 3 mins, with Alonzo pilot)

- Based on Harley's presentation on Tello SNAP! interaction
- New aspect: Object detection, Jetson
- Challenges
  - Video stream from Tello drone to SNAP! (25 fps)
  - Video stream from SNAP! to Jetson (extacting stage in base64 format, send message, wait response, sequential, 7 fps)
  - Receive response from Jetson to SNAP! (bounding box, class label, coordinate transformation to the stage)
- Frame rate incl. analysis is 7 fps
- Problem (not serious): Realtime delay (latency) within the Tello drone video stream!
- TODO: Short video!

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