

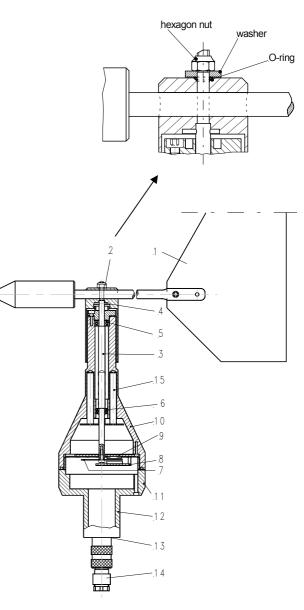
### 4123.0000 BG

GROUP 4	WIND
NO.	4123.0000
VERSION / DATE / NAME	08 / 01.2017 / Zi

### FIG. 1: MECHANICAL DESIGN

Detail 2





### DESCRIPTION

This sensor is designed for the acquisition and electronic transmission of wind direction data. It is suitable for applications in the field of meteorology and environmental monitoring, e. g. for automatic weather stations, at airports, on research vessels, at industrial sites, for mobile measuring systems etc.. The instrument's rugged construction and its dust- and water repellent surface, as well as the optional high performance heating enable heavy duty applications like wind energy measurement or operation under severe climatic conditions.

Thanks to various simultaneously usable outputs and further options there is a wide range of measuring tasks (refer to "ordering code").

# MECHANICAL DESIGN AND PRINCIPLE OF OPERATION

The sensor comprises a wind vane system which is continuously kept parallel to the local wind direction through the occuring wind pressure. The vane position is transmitted by the shaft to the angular encoder unit. The mechanical design can be noted on fig. 1:



The fin (1) is made of anodized aluminium sheet metal. The supporting arm and the counter balance are made of stainless steel. The rotary head, made anodized aluminium, is fastened to the vertical shaft (3) by a hexagon nut with washer and O-ring sealing (2). In order to maintain the correct position after replacement there is a pin (4) in the shaft, engaging a groove when lowering the rotary head. The shaft is made of stainless steel and is guided by two precision ball bearings (5, 6). The code wheel (7) is fastened to the lower end of shaft and is placed between the two print boards (8, 9), carrying the 8-line light barrier.

By interrupting this light barrier, the angular position is detected by means of an 8 bit Gray Code. The housing consists of an upper (10) and a lower part (11). These parts, as well as the hub, are made of a special coated aluminium alloy, featuring water repellence and corrosion protection. Sealing between upper and lower part is achieved by means of an O-ring. The pivot (12) at the lower part has a size 34 x 40 mm and may be fastened to a crossarm or similar mounting device. At the lower end of the pivot there is a connector socket (13) and plug (14). At the top section a white mark is located. If the corresponding mark which is engraved in the rotary head is brought exactly to the same position, the sensor supplies a signal corresponding North direction. When installing the sensor an adequate geographic alignment must be carried out (refer to section "Installation"). A built-in heating features operation in cold climate.

# ELECTRICAL DESIGN AND PRINCIPLE OF OPERATION

When moving the wind vane, the wheel of the angular encoder is turned so that, depending on the wind direction, a corresponding digital signal is supplied. The subsequent electronic circuitry converts this signal to a serial output, resp. to additional analogue signals (refer to "Technical Data").

The serial data output (TTL) corresponds an RS 232 structure, with 600 Bd, 8 bit, 1 start bit, 2 stop bit, no parity bit.

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### CONSTRUCTION OF THE HEATING

The heating consists of a power transistor, controlled by a separate circuitry with temperature sensor.

The high performance heating versions are equipped with 4 cylindrical heaters (15) with 60 W max. heating power.

For further data processing (averaging etc.), refer to datalogger COMBILOG, type 1020; catalogue group 1.

#### **TECHNICAL DATA**

	0.000
Measuring range:	360°
Max. load:	100 m/s
Threshold at 90° initial deflection:	< 0.2 m/s
Damping ratio at v = 3 m/s and initial deflection = 15°:	< 0.3
Compliances:	WMO Guide No. 8/7th ed. VDI 3786, T.2, 12/2000 MEASNET
Power supply:	Electronics:
	<b>Type 4123.0000</b> : 1030 VDC; < 5 mA at 12 V
	<b>Type 4123.1000:</b> 1030 VDC; 3575 mA at 12 V
	Heating: 1030 VDC; approx. 7 W
	High performance heating: 24 VDC; approx. 60 W

#### OUTPUT

digital:	serial 8 bit Gray code,
	RS 232 compatible, 600Bd, 8 data bit, 1 startbit,
	2 stopbit, no parity, TTL level
additional, with version 4123.1:	
analogue:	020 mA

4...20 mA 3 phase signal for direct connection of analogue instruments.



Admissible load:	approx. 400 Ω
Heating system:	Thermostat controlled, max. 7 W
High perf. heating:	max. 60 W
Operating temperature:	-25+80 °C -40+80 °C with high performance heating
Protection class:	IP 65, when operated upright
Housing material:	Aluminium alloy
Connection:	12 p. connector, water- and dust proof acc. to IP 67
Measuring cable:	LiY(C)Y 0.25 mm2 (not included)
Weight:	approx. 1.015 kg

#### DIMENSIONS

Total height:	approx. 370 mm
Max. turning radius:	350 mm
Max. housing $\varnothing$ :	80 mm
Pivot:	Ø 34 x 40 mm

#### **ORDERING CODE**

Wind direction sensor, 8 bit Gray Code with serial output, TTL level; with built-in heating.	4123.0000
Wind direction sensor, 8 bit Gray Code with serial output, TTL level; analogue outputs 020 mA, 420 mA as well as 3 phase signal for direct connection of analogue instruments, with built-in heating.	4123.1000
As 4123.0000, but with high performance heating.	4123.0100
As 4123.1000, but with high performance heating.	4123.1100

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### **OPERATING INSTRUCTION**

#### INSTALLATION

The wind direction sensor has to be placed at a suitable height (for example 10 m for meteorological measurement of the ground wind). There is a number of tilting masts of different heights from 5 to 15 m available for this purpose. Lattice masts up to 80 m height and various telescopic masts can also be supplied (refer to product group 9). In any case it has be taken care to avoid zones of lee or turbulences!

Before mounting the sensor, the wind vane is placed onto the shaft and turned until its groove matches the pin. After that the hexagonal nut is screwed on and tightened. The correct position of the vane on the shaft may also be checked after completing installation by controlling if the notch at the end of the shaft points to the same direction as the white mark on the side of the rotary head.

#### ATTENTION .

This unit must only be operated after the wind vane has been installed and the hexagonal nut has been tightened well; otherwise (during rain) water could penetrate into the housing!

Installation is carried out according to fig. 2. The sensor can be mounted on a pipe stud  $\emptyset$  35 mm, or alternatively on an adapter type 9023. For crossarm installation a clamp type 9022 can be used. For operation in connection with a speed sensor, the use of an L-shaped or U-shaped crossarm, type 9040, is recommended. The installation of a lightning rod is recommended for measuring sites in regions accordingly threatened. Power- and measuring lines shall be protected by suitable over voltage protection devices! North adjustment is performed by using a compass or exactly determined true bearings of targets in the field. Hereby the two white marks on the housing and the rotary head should be opposite to each other when the vane is pointing to true North.

Installation on top of wind turbines, ship masts or similar structures with tilt motion, vibration or other dynamic force requires a rugged, eventually shock absorbing, suspension construction.

In this case, please contact us for further consultance.

#### CONNECTION

Connection has to be carried out according to fig. 3.



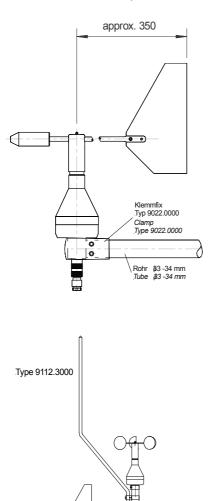
#### MAINTENANCE

The wind direction sensor type 4123 operates maintenance-free!

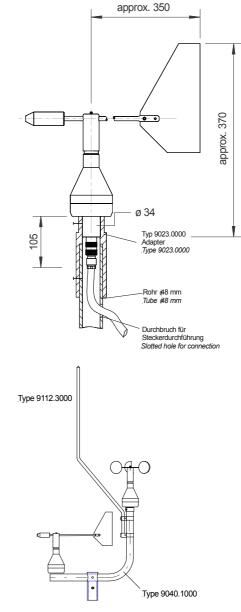
Ball bearings, however, are subject to attrition.

#### **FIG. 2: MOUNTING OPTIONS**

(standard from - stock solutions)



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Technical data are subject to change!

Type 9040.0000

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Therefore an occasional check for plausibility (during low wind speed) is recommended: If a decrease of sensitivity is detected, the shaft / ball bearing assembly should be replaced.

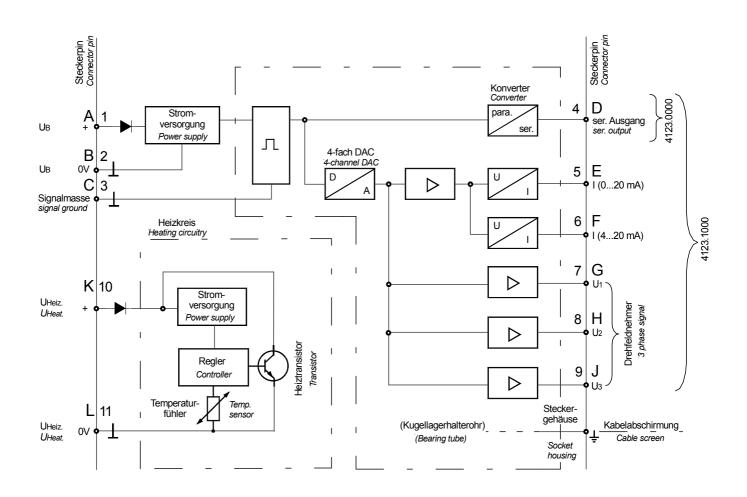


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# Wind Direction Sensor

### FIG. 3: BLOCK DIAGRAM / CONNECTION PLAN





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### GRAYCODETABELLE

2.5127122.587242.55.0126125.086245.07.5124127.584247.510.0125130.085250.012.5121132.581252.515.0120135.080255.017.5122137.582257.520.0123140.083260.0	198 196 197 193 192 194 195 203
7.5124127.584247.510.0125130.085250.012.5121132.581252.515.0120135.080255.017.5122137.582257.520.0123140.083260.0	196 197 193 192 194 195 203
10.0125130.085250.012.5121132.581252.515.0120135.080255.017.5122137.582257.520.0123140.083260.0	197 193 192 194 195 203
12.5121132.581252.515.0120135.080255.017.5122137.582257.520.0123140.083260.0	193 192 194 195 203
15.0120135.080255.017.5122137.582257.520.0123140.083260.0	192 194 195 203
15.0120135.080255.017.5122137.582257.520.0123140.083260.0	192 194 195 203
17.5122137.582257.520.0123140.083260.0	194 195 203
20.0 123 140.0 83 260.0	195 203
	203
22.5 115 142.5 91 262.5	
25.0 114 145.0 90 265.0	202
27.5 112 147.5 88 267.5	
30.0 113 150.0 89 270.0	
32.5 117 152.5 93 272.5	
35.0 116 155.0 92 275.0	
37.5 118 157.5 94 277.5	
40.0 119 160.0 95 280.0	
42.5 103 162.5 31 282.5	
45.0 102 165.0 30 285.0	
47.5 100 167.5 28 287.5	
50.0 101 170.0 29 290.0	
52.5 97 172.5 25 292.5	
55.0 96 175.0 24 295.0	
57.5 98 177.5 26 297.5	
60.0 99 180.0 27 300.0	
62.5 107 182.5 155 302.5	
65.0 106 185.0 154 305.0	
67.5 104 187.5 152 307.5	
70.0 105 190.0 153 310.0	
72.5 109 192.5 157 312.5	
75.0 108 195.0 156 315.0	
77.5 110 197.5 158 317.5	
80.0 111 200.0 159 320.0	
82.5 79 202.5 223 322.5	
85.0 78 205.0 222 325.0	246
87.5 76 207.5 220 327.5	244
90.0 77 210.0 221 330.0	
92.5 73 212.5 217 332.5	
95.0 72 215.0 216 335.0	
97.5 74 217.5 218 337.5	
100.0 75 220.0 219 340.0	243
102.5 67 222.5 211 342.5	251
105.0 66 225.0 210 345.0	250
107.5 64 227.5 208 347.5	248
110.0 65 230.0 209 350.0	249
112.5 69 232.5 213 352.5	253
115.0 68 235.0 212 355.0	252
117.5 70 237.5 214 357.5	254
120.0 71 240.0 215 360.0	255

Technical data are subject to change!

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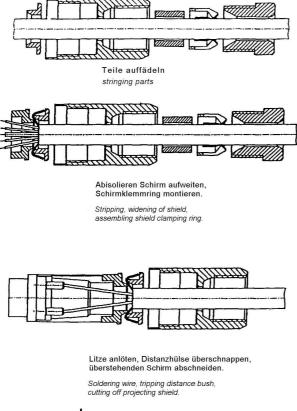
CONTACT ~|~ P + 49.~(0)~40.~839~600 - ~0~|~ F + 49.~(0)~40.~839~600 - 18~|~ E~info~@~th-friedrichs.de

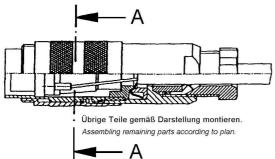


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# Wind Direction Sensor

### HANDLING INSTRUCTION, CONNECTOR





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### **SECTION A-A**

